APPLICATION NO. 10/772,597

INVENTION: Decisioning rules for turbo and convolutional decoding

INVENTORS: Urbain A. von der Embse

Currently amended CLAIMS

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CLAIMS

WHAT IS CLAIMED IS:

10 Claim 1. (currently amended) A means method for the performing a new turbo decoding algorithm using a-posteriori probability p(s,s'|y) in equations (13) of the invention disclosure of the decoder trellis states s',s for the received codeword k-1,k conditioned on the received symbol set y = {y(1),y(2),...,y(k-1),y(k),...,y(N)} for defining the maximum a-posteriori probability MAP, comprising: in turbo decoding and which comprises:

using a new statistical definition of the MAP logarithm likelihood ratio L(d(k)|y) in equations (18)

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$$L(d(k))|y) = ln[\Sigma_{(s,s'|d(k)=+1)} p(s,s'|y)] - ln[\Sigma_{(s,s'|d(k)=-1)} p(s,s'|y)]$$

equal to the natural logarithm of the ratio of the aposteriori probability p(s,s'|y) summed over all state
transitions $s' \rightarrow s$ corresponding to the transmitted data d(k)=1 to the p(s,s'|y) summed over all state transitions $s' \rightarrow s$ corresponding to the transmitted data d(k)=0,

using a factorization of the a-posteriori probability p(s,s'|y)

in equations 13 into the_product of the a-posteriori
probabilities__p(s'+y(j<k)),p(s+s',y(k)), p(s+y(j>k))

$$p(s,s'|y)=p(s|s',y(k))p(s|y(j>k))p(s'|y(j$$

using a turbo decoding forward recursion equation for evaluating

said a-posteriori probability p(s'|y(j<k)) using said

p(s|s',y(k)) as the state transition a-posteriori

probability of the trellis

 $p(s|y(j< k), y(k)) = \sum_{all s'} p(s|s', y(k)) p(s'|y(j< k))$

for evaluating said a-posteriori probability p(s'|y(j < k)) in equations 14 using p(s|s',y(k)) as the state transition a-posteriori probability of the trellis transition path $s' \rightarrow s$ to the new state s at k from the previous state s' at k-1 and given the observed symbol y(k) to update these recursions for the assumed value of the user data bits d(k) equivalent to the transmitted symbol x(k) which is the modulated symbol corresponding to d(k),

using a turbo decoding backward recursion equation for evaluating

said a posterior probability p(s|y(j>k)) using said

p(s'|s,y(k)) as the state transition a posteriori

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$$p(s'|y(j>k-1) = \sum_{all \ s} p(s|y(j>k))p(s'|s,y(k))$$

for evaluating the a-posterior probability p(s|y(j>k)) in

equations 15 using said p(s'|s,y(k)) = p(s|s',y(k)) as the

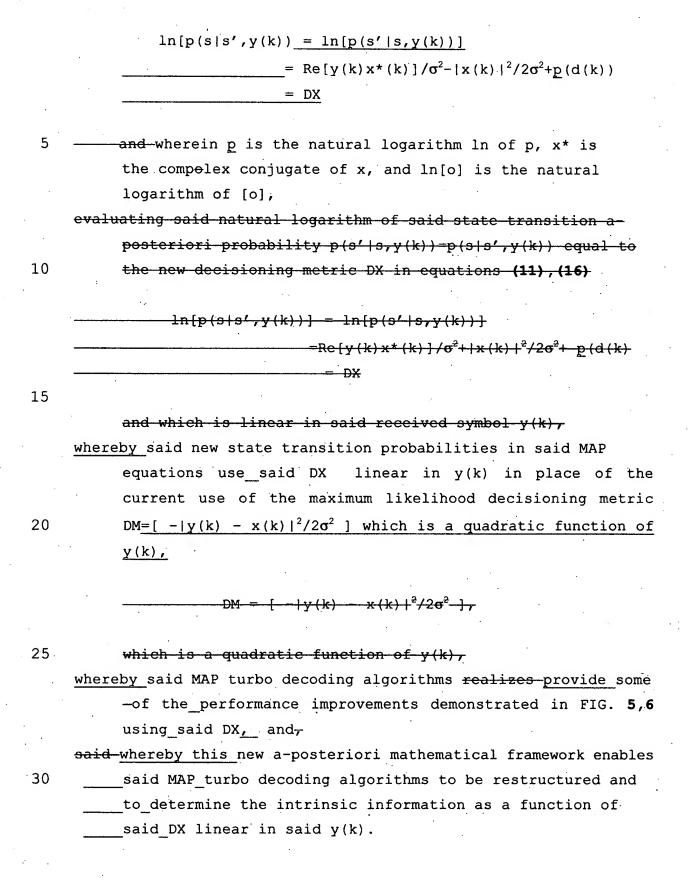
state transition a-posteriori probability of the trellis transition pa

equivalent to said transmitted symbol x(k) which is the

modulated symbol corresponding to said d(k) and where said

p(s'|s,y(k))=p(s|s',y(k)),

evaluating the natural logarithm of the state transition a
posteriori probability p(s|s',y(k))=p(s'|s,y(k)) as a function which is linear in the received symbol $\frac{y(k)}{y(k)}$ equal to the new decisioning metric DX in equations 11,16, defined by equation



Claim 2. (currently amended) Wherein in claim 1 aA method for performing means for said a new convolutional decoding algorithm in saidusing the MAP a-posteriori probability p(s,s'|y) and which comprises in equations 13, comprising::

using a new maximum a-posteriori principle which maximizes the a-posteriori probability p(x|y) of the transmitted symbol x given the received symbol y to replace the current maximum likelihood principle which maximizes the likelihood probability p(y|x) of y given x for deriving the forward and the backward recursive equations to implement convolutional decoding,

using said—the factorization of said—the a-posteriori probability—p(s,s'|y) in equations 13 into the product of said aposteriori probabilities p(s'|y(j< k)), p(s|s',y(k)), p(s|y(j>k)) to identify the convolutional decoding forward state metric $a_{k-1}(s')$, backward state metric $b_k(s)$, and state transition metric $p_k(s|s')$ as the a-posteriori probability factors

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$$p_{k}(s|s') = p(s|s',y(k))$$

$$b_{k}(s) = p(s|y(j>k))$$

$$a_{k-1}(s') = p(s'|y(j$$

using a convolutional decoding forward recursion equation in

equations 14 for evaluating said a-posteriori probability $a_k(s) = p(s|y(j < k), y(k))$ using said $p_k(s|s') = p(s|s', y(k))$ as said state transition probability of the trellis transition path $s' \rightarrow s$ to the new state s at k from the previous state s' at k-1,

using a convolutional decoding backward recursion equation in equations 15 for evaluating said a-posteriori probability $b_k(s) = p(s|y(j>k))$ using said $p_k(s'|s) = p(s'|s,y(k))$ as said state transition probability

of the trellis transition path s→s' to the new state s' at k-1 from the previous state s at k, evaluating the natural logarithm of said state_transition a-posteriori probabilities

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$$ln[p_k(s'|s)] = ln[p(s'|s,y(k))]$$
= ln[p(s|s',y(k))]
= ln[p_k(s|s')]
= DX

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equal to said the new decisioning metric DX in equations 16, and,

implementing said convolutional decoding algorithms to

realizeobtain some of the performance improvements

demonstrated in FIG. 5,6 using said DX.

Claim 3. (currently amended) Wherein_in claim 42 A means

fora method for implementing the new convolutional decoding

20 recursive equations, which calculate said MAP a-posteriori

probability p(s,s'|y) said method comprising: and which comprises:

said_implementing in equations 14 a forward recursion equation

for evaluating—said_the—natural logarithm, ak, of ak using

said_pk=ln[p(s|s',y(k))] as the natural logarithm said_of

the___state__transition a-posteriori probability

pk=ln[p(s|s',y(k))] of the trellis transition path s' >> s to

the new state s at k from the previous state s' at k-1,

30 $\underline{\mathbf{a}}_{k}(s) = \max_{s} \left[\underline{\mathbf{a}}_{k-1}(s') + \underline{\mathbf{p}}_{k}(s|s')\right]$ $= \max_{s} \left[\underline{\mathbf{a}}_{k-1}(s') + DX(s|s')\right]$ $= \max_{s} \left[\underline{\mathbf{a}}_{k-1}(s') + Re\left[y(k)x^{*}(k)\right]/\sigma^{2} - |x(k)|^{2}/2\sigma^{2} + p(d(k))\right]$

which is equation and is

wherein said $DX(s|s')=p_k(s|s')=p_k(s'|s)=DX(s'|s)=DX$ is said the new decisioning metric, and

for evaluating said—the natural logarithm, b_k of b_k using said— p_k = $\ln[p(s'|s,y(k))]$ = $\ln[p(s|s',y(k))]$ as the natural logarithm of said state transition a-posteriori probability p_k = $\ln[p(s'|s,y(k))]$ = $\ln[p(s|s',y(k))]$ of the trellis transition path $s \rightarrow s'$ to the new state s' at k-1 and is equation

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 $\underline{b}_{k-1}(s') = \max_{s} [\underline{b}_{k}(s) + DX(s'|s)] \underline{-and_{r}}$

said decoding algorithms realize some of the performanceimprovements demonstrated in FIG. 5,6 using said DX.